Astro 210 Lecture 8 Sept 10, 2010

Announcements

- HW2 due now
- HW3 available, due next Friday
- HW1 graded, scores on Compass, papers back next time
- last chance! register your iClicker; link on course webpage
- Bigshot astronomer coming next week: Iben Distinguished Lecturer: Tony Tyson lead scientist on top new telescope for 2010-2020 decade! "Exploring the Dark Side of the Universe"

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7pm Wed Sept 15, Foellinger; more info on course page

Last Time: Sir Isaac Weighs In

Newton's Laws of motion I. inertia *Q: just a special case of Newton II?* II. $\vec{F} = m\vec{a}$ *Q: fortunetelling & archæology?* III. action-reaction

Q: when/where/to what do Newton's laws of motion apply?

Newtonian Gravitation

Q: magnitude of gravity force between masses m and M with distance r?

Q: direction of the force?

Ν

Newton's laws sweeping in scope! as stated they, should apply to *any* motion of *any* object of *any* size, shape, or speed, with *any* forces acting at *any* time

in fact: for all of everday life, and indeed for much of the cosmos and its history, Newton's laws work fantastically well!

but we will see soon: they are not the last word under very extreme (and very interesting!) conditions Newton's laws fail...

 $_{\omega}$ but to understand the significance of Newton's limitations first need to appreciate his most spectacular success...

Angular Momentum

For point mass, angular momentum defined as

$$\vec{L} = \vec{r} \times \vec{p} = m\vec{r} \times \vec{v} \tag{1}$$

where \times is vector cross product *diagram: perspective:* $\vec{r}, \vec{p}, \vec{L}$

What is time change of angular momentum?

$$\frac{d}{dt}\vec{L} = m\dot{r} \times \vec{v} + m\vec{r} \times \dot{v}$$
(2)

$$= m\vec{v}\times\vec{v}+m\vec{r}\times\vec{a} \tag{3}$$

$$= \vec{r} \times \vec{F} = \vec{\tau}$$
 torque (4)

angular counterpart of Newton II

- $d\vec{p}/dt = \vec{F}$: net (linear) force changes linear momentum
- $d\vec{L}/dt = \vec{\tau}$: net twisting force = torque changes angular momentum

iClicker Poll: Orbits and Angular Momentum I

For an object in a Keplerian (elliptical) orbit around the Sun Consider the **directions** of angular momentum at *perihelion*, and *aphelion*

How do these compare?



- the two vectors are parallel
- В
- the two vectors are antiparallel



none of the above

Gravity and Angular Momentum

in general: angular momentum $\vec{L} = m\vec{r} \times \vec{v}$ torque $\vec{\tau} = \vec{r} \times \vec{F} = d\vec{L}/dt$

when force is due to gravity, torque is:

$$\frac{d}{dt}\vec{L} = \vec{\tau} = -\vec{r} \times G\frac{mM}{r^3}\vec{r} = 0$$
(5)

so if force is gravity:

- torque is *zero*! ...and so
- angular momentum is **conserved!**
- \circ Q: what about gravity force gauranteed that zero?

What Keeps the Earth in Orbit?

circular orbit \rightarrow centripetal accel. angular speed $d\theta/dt = \omega = 2\pi/P = const$, r = const $a = -\omega^2 r = -v^2/r$ diagram: show \vec{v} , \vec{r} , \vec{a}

Newton II: acceleration demands net force but Newton gravity supplies a force!

→ Newtonian gravity is crucial and necessary ingredient for understanding the dynamics of planetary motion but have to see how the detailed predictions compare with observation

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Program:

- assume Newtonian gravity controls planetary motion
- that is, for any planet let $\vec{F}_{net} = \vec{F}_{Sun-planet}$
- input this into Newton's laws
- \bullet turn mathematical cranks \rightarrow predict orbits
- compare predictions with observation

Solutions: Orbits

For attractive inv. sqare force, oribts are cross sections of cone: circle, ellipse, parabola, hyperbola, line *transp: oribts*

Circle eccentricity e = 0at each point: $F = ma = mv_{C}^{2}/r$ $\Rightarrow GMm/r^{2} = mv_{C}^{2}/r$ \Rightarrow circular orbits have speed $v_{C} =$

 $v_{\mathsf{C}} = \sqrt{\frac{GM}{r}}$

 $_{\odot}$ ex: circular speed 1 AU from Sun $v_{\rm C} = 3 \times 10^4$ m/s

Kepler from Newton

Kepler I: Orbits are ellipses

Newton: bound orbits due to gravity are ellipses: check!

Kepler II: Equal areas in equal times

Newton: consider small time interval dtmove angle $d\theta = \omega dt$ sweep area diagram: top view: path, $d\theta, \vec{r}, \vec{v}, \vec{v}_t$

$$dA = \frac{1}{2}r^2d\theta = \frac{1}{2}r^2\omega dt \tag{6}$$

(7)

but $\omega = v_{\theta}/r$, where $\vec{v_{ heta}} \perp \vec{r}$

 \Rightarrow swept area

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 $dA = \frac{1}{2}r^2 \frac{v_\theta}{r} dt = \frac{1}{2}rv_\theta dt$

 \Rightarrow swept area

$$dA = \frac{1}{2}r^2 \frac{v_\theta}{r} dt = \frac{1}{2}rv_\theta dt \tag{8}$$

finally,
$$rv_{\theta} = |\vec{r} \times \vec{v}| = |\vec{L}|/m$$

Q: why?, so

$$dA = \frac{1}{2} \frac{L}{m} dt$$
(9)

Woo hoo! were' home free! Q: why?

But L = const for radial force $(\vec{r} \times \vec{F} = 0)$ so

$$\frac{dA}{dt} = \frac{L}{2m} = const \tag{10}$$

Kepler II! \rightarrow comes from ang. mom. cons.!

iClicker Poll: Orbits and Angular Momentum II

Consider two objects at 1 AU:

- a planet in a circular orbit
- a spacecraft moving directly towards the Sun

Which has the larger *magnitude* of angular momentum?







either, depending on the speed of the spacecraft

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Kepler III: $a^3 = kP^2$

Newton: can prove generally for elliptical orbits bad news: price is lotsa algebra

good news: simple to do for circular orbits circular $\rightarrow r = a$, and $v^2 = GM/a$ but also $v = 2\pi a/P \ Q$: why?

$$v^{2} = \left(\frac{2\pi a}{P}\right)^{2} = \frac{4\pi^{2}a^{2}}{P^{2}}$$
 (11)
 $- \frac{GM}{GM}$ (12)

$$\Rightarrow a^3 = \left(\frac{a}{4\pi^2}\right)P^2 \tag{12}$$

check!

bounus: $k = GM/4\pi^2$ depends on mass of central object \rightarrow same k for all planets